

Characterizing the Vertical Stratification of the Earth's Planetary Boundary Layer (PBL) with GNSS Radio Occultation

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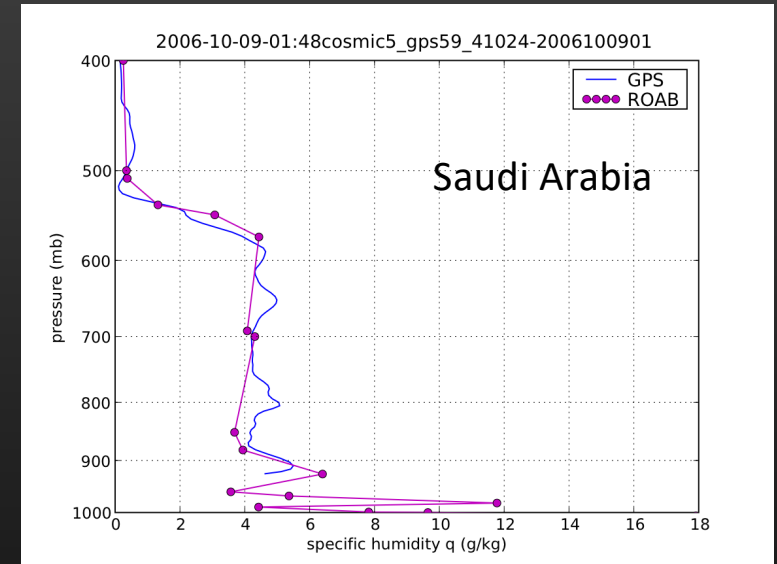
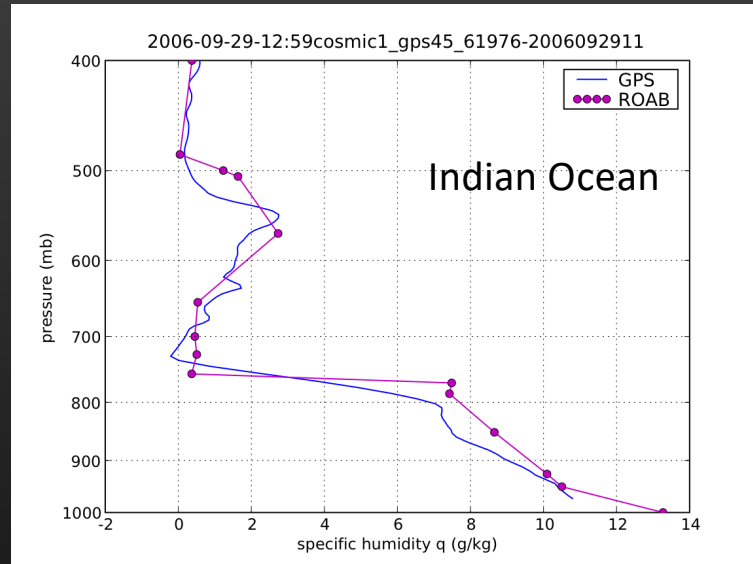
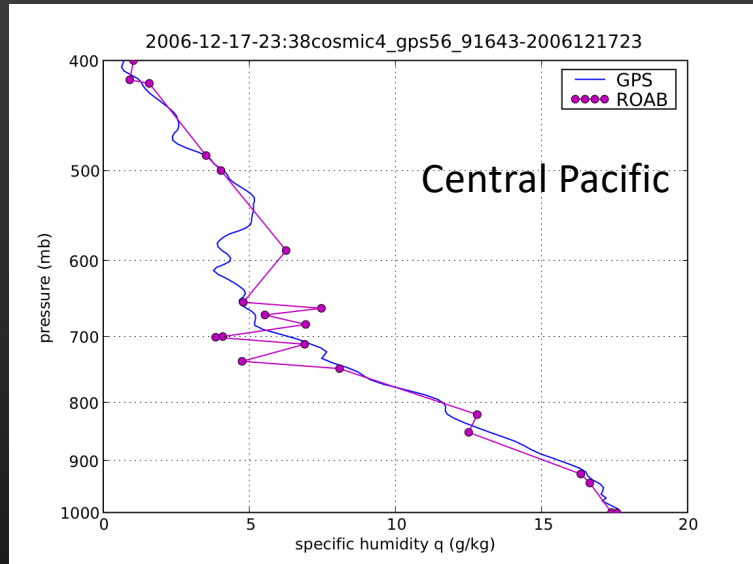
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Beyond PBL heights...

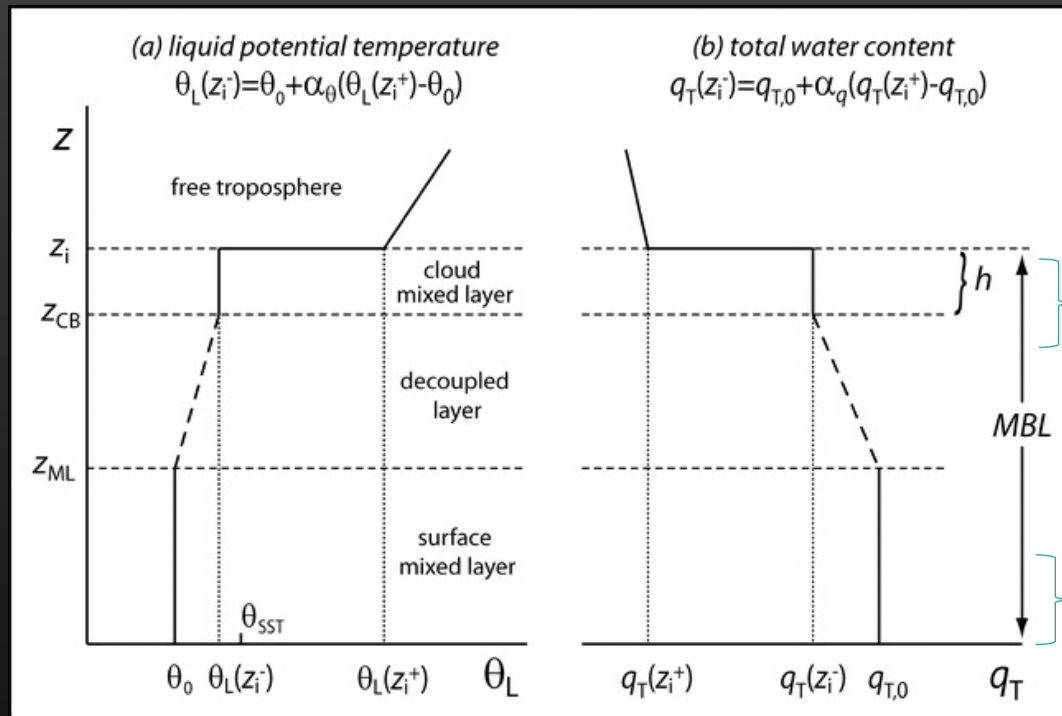


These examples of COSMIC humidity profiles collocated with ROABs show that RO provide vertical structures within the PBL, which has been underutilized, partly due to retrieval uncertainty (N-bias, penetration depth)

Outline

- Decoupling parameter (DCP) as bulk characterization of PBL stratification
- Uncertainty estimates
- Validation with radiosondes
- DCP climatology and model comparisons
- RO/PBL in US Decadal Survey

Decoupling Parameter (DCP)



Wood and Bretherton, *J. Clim.*, 2004

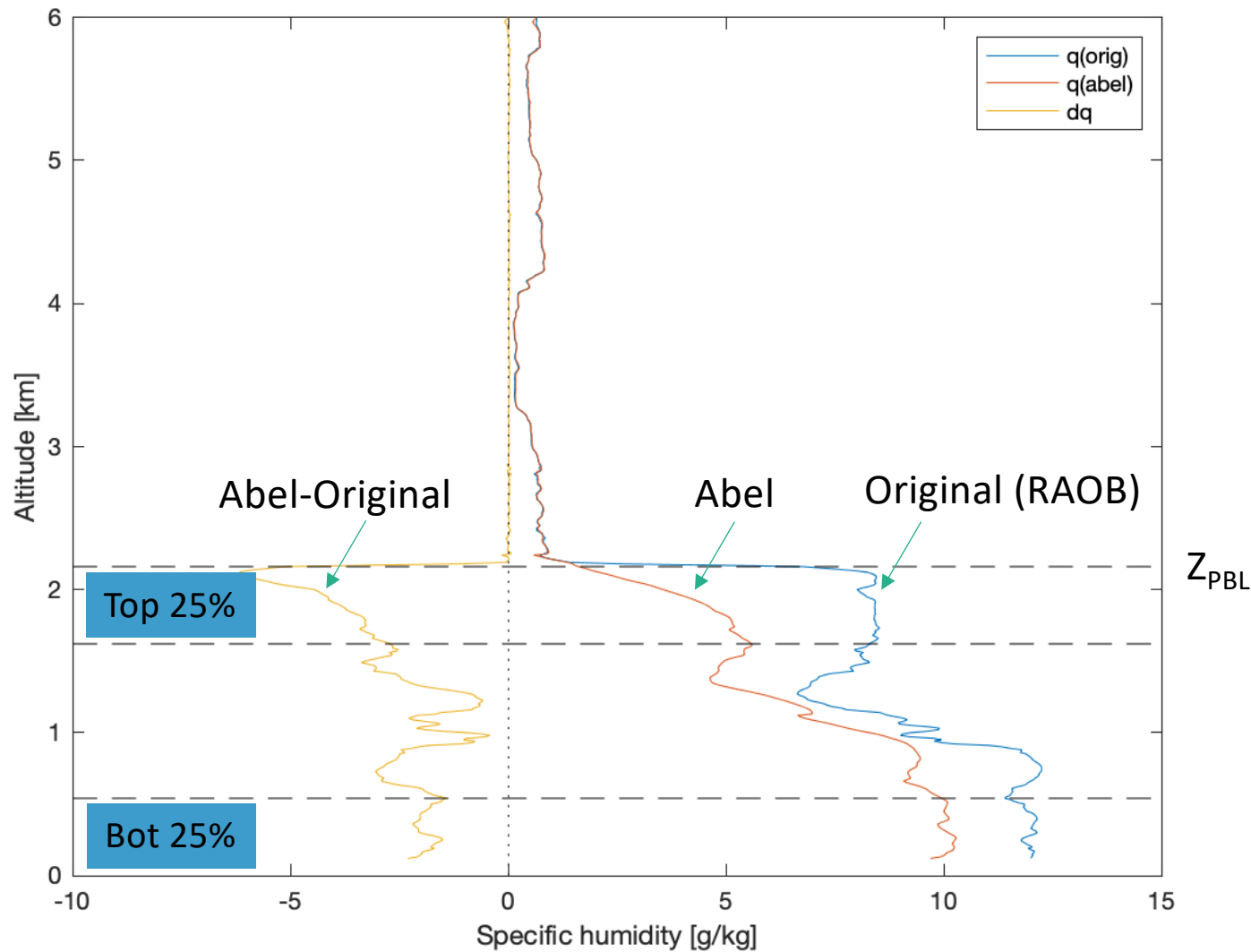
We define the decoupling parameter as [Jones et al., ACP, 2011]

$$DCP = q(\text{bot}) - q(\text{top})$$

where bot, top = bottom (top) 25% of the PBL

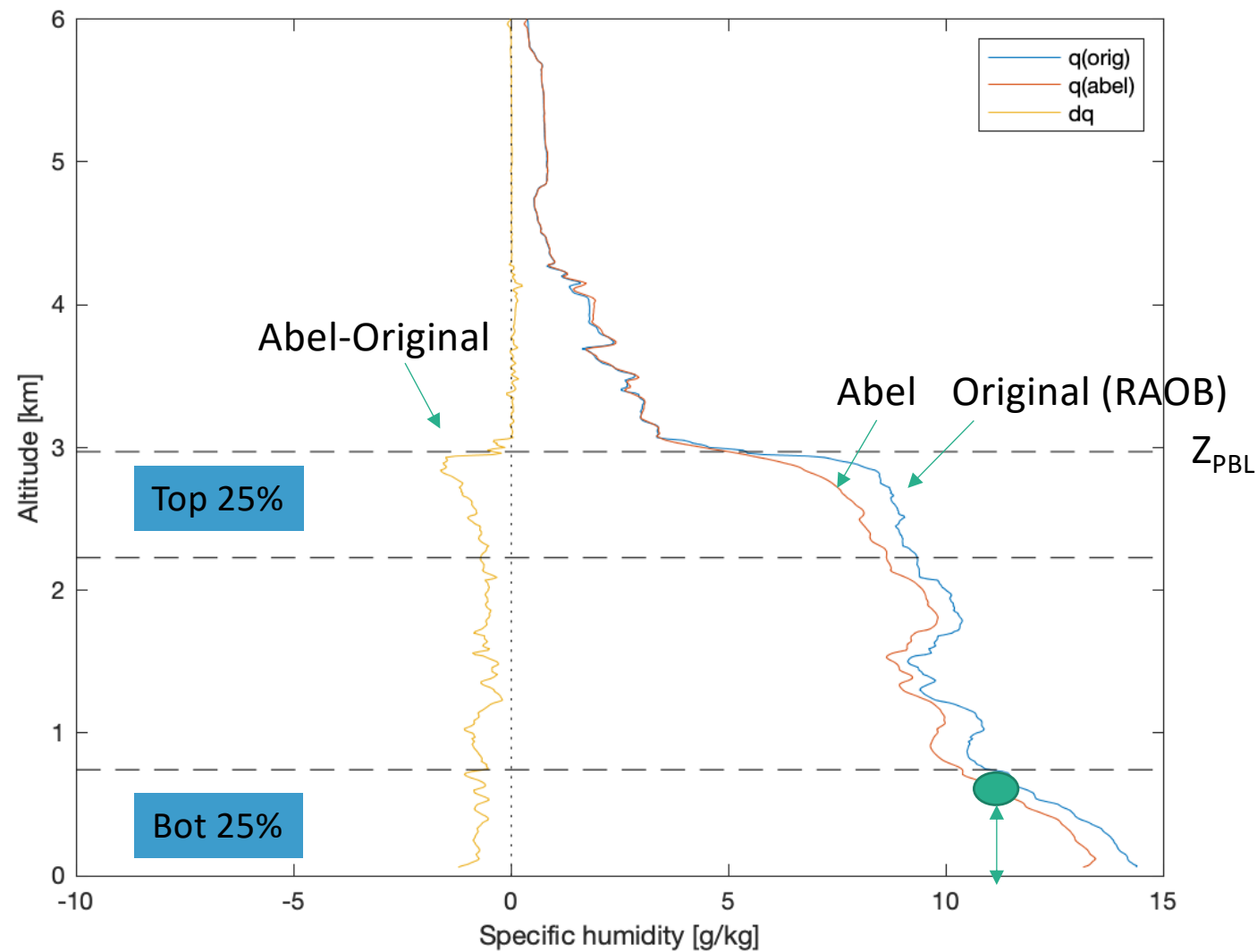
Normalized decoupling parameter:
 $DCP_N = DCP / \langle q(PBL) \rangle$ (not shown here)

Uncertainty from Retrieval Error (Example 1)



Ducting-induced negative N-bias tends to overestimate DCP because $q(\text{top})$ is reduced more than $q(\text{bot})$.

Uncertainty from Retrieval Error (Example 2)



Insufficient penetration tends to underestimate DCP because near-surface q tends to be the same or slightly larger.

Comparison with MAGIC RAOB

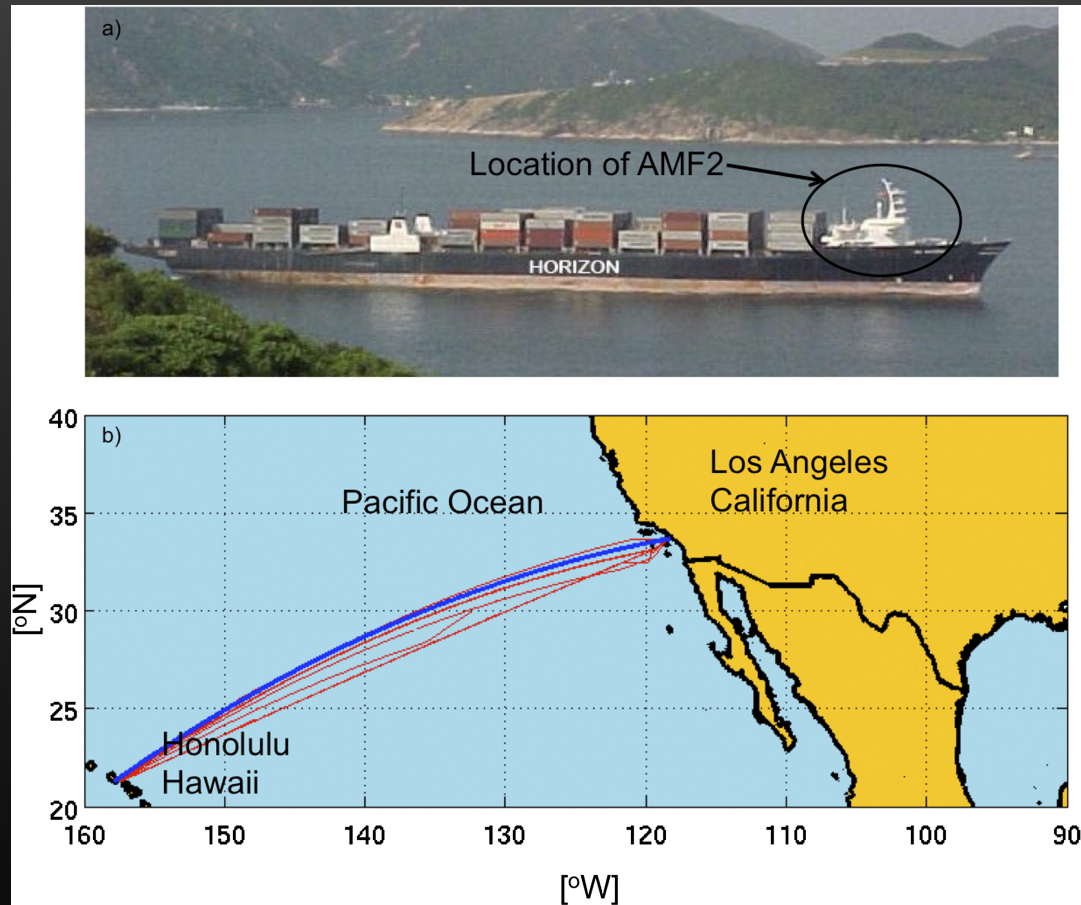
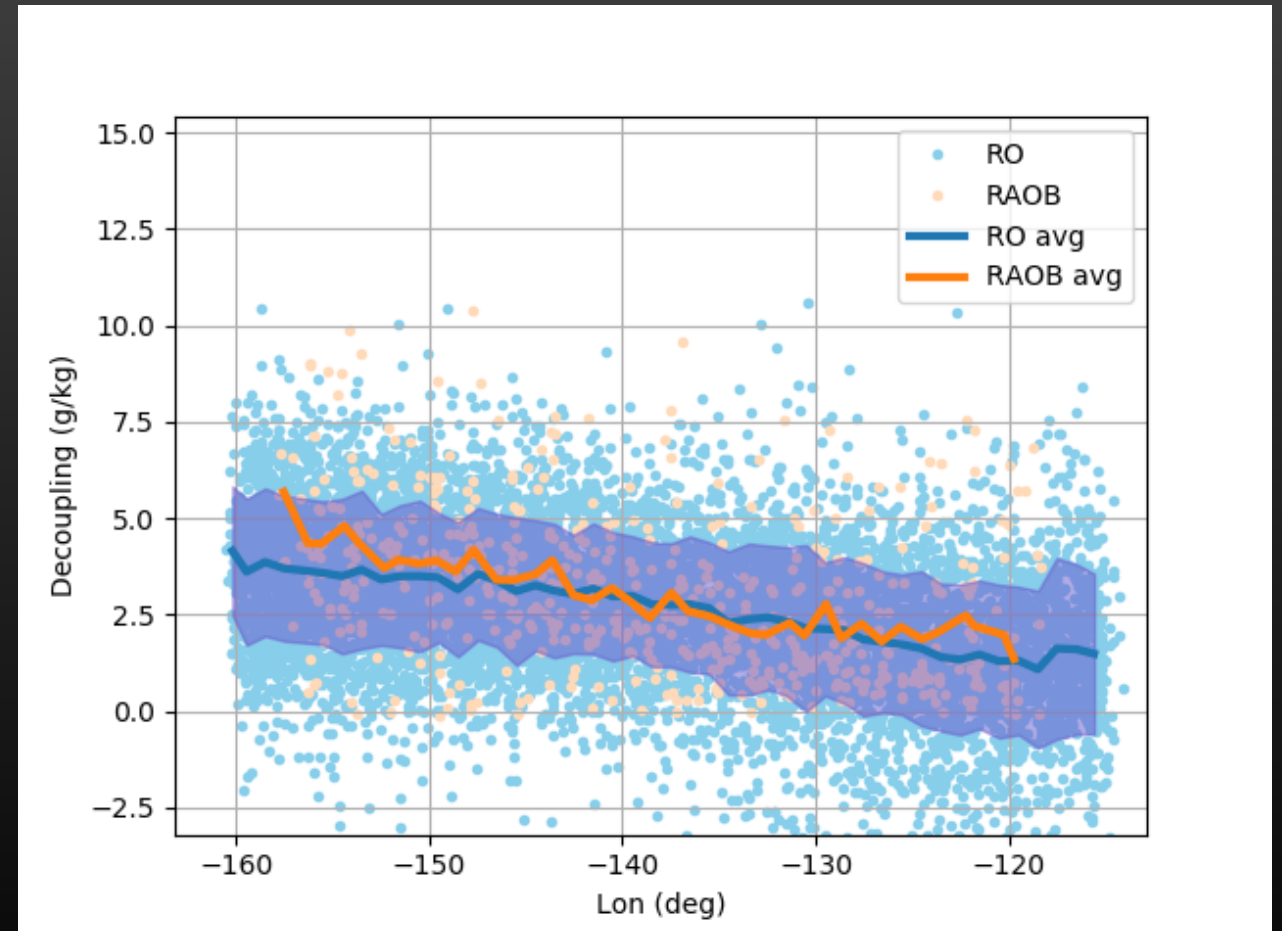
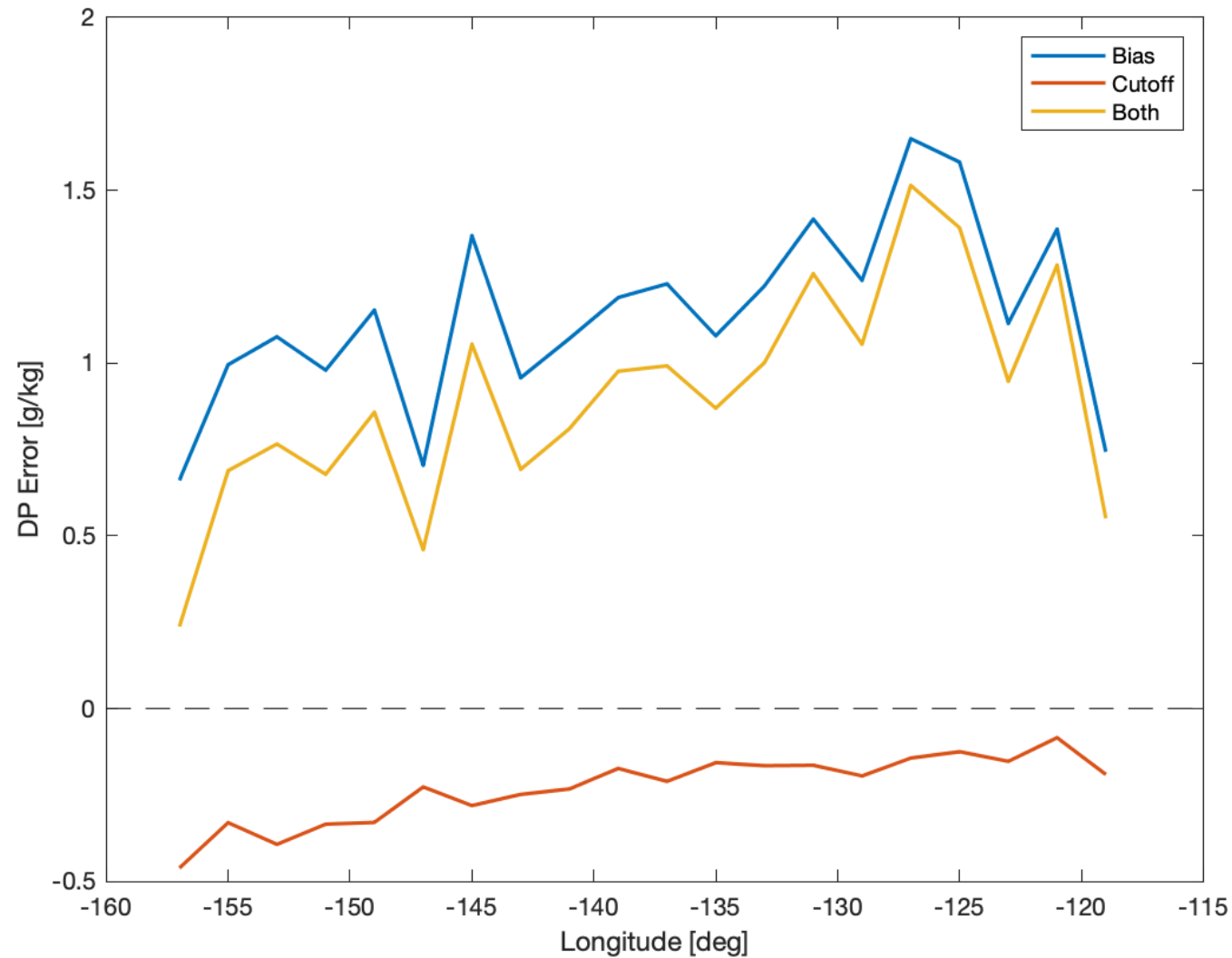


Figure from Zhou et al., J Clim. 2015

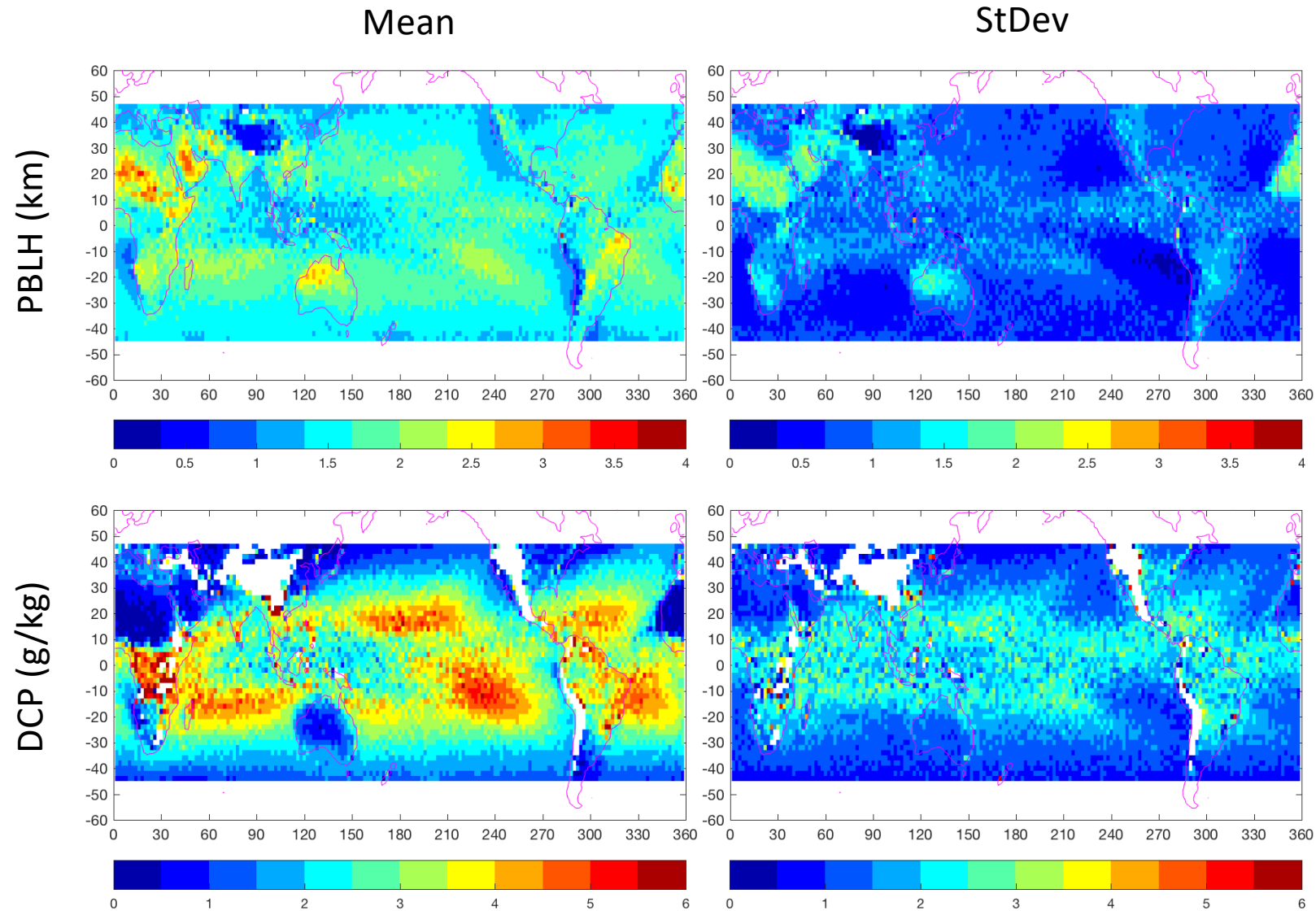


Good agreement between RO and RAOB on average!

Uncertainty from Retrieval Error (MAGIC)



- Positive DCP error on the order of ~ 1 g/kg arises mainly from ducting-induced negative N-bias.
- However, actual comparison between COSMIC and MAGIC shows better agreement than 1 g/kg
 - Sampling?
 - Other retrieval biases?



From ~ 10 years of COSMIC and TSX data

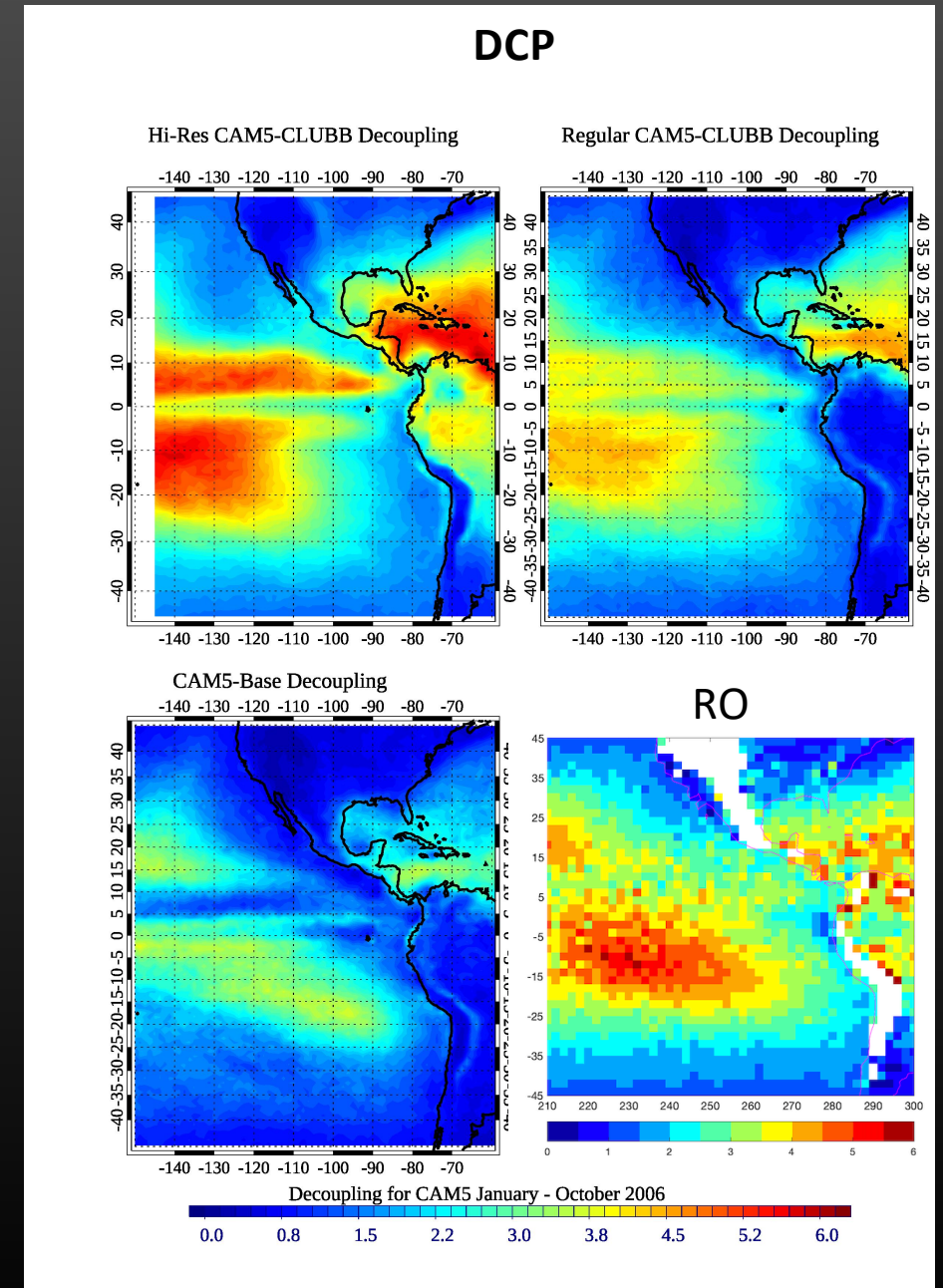
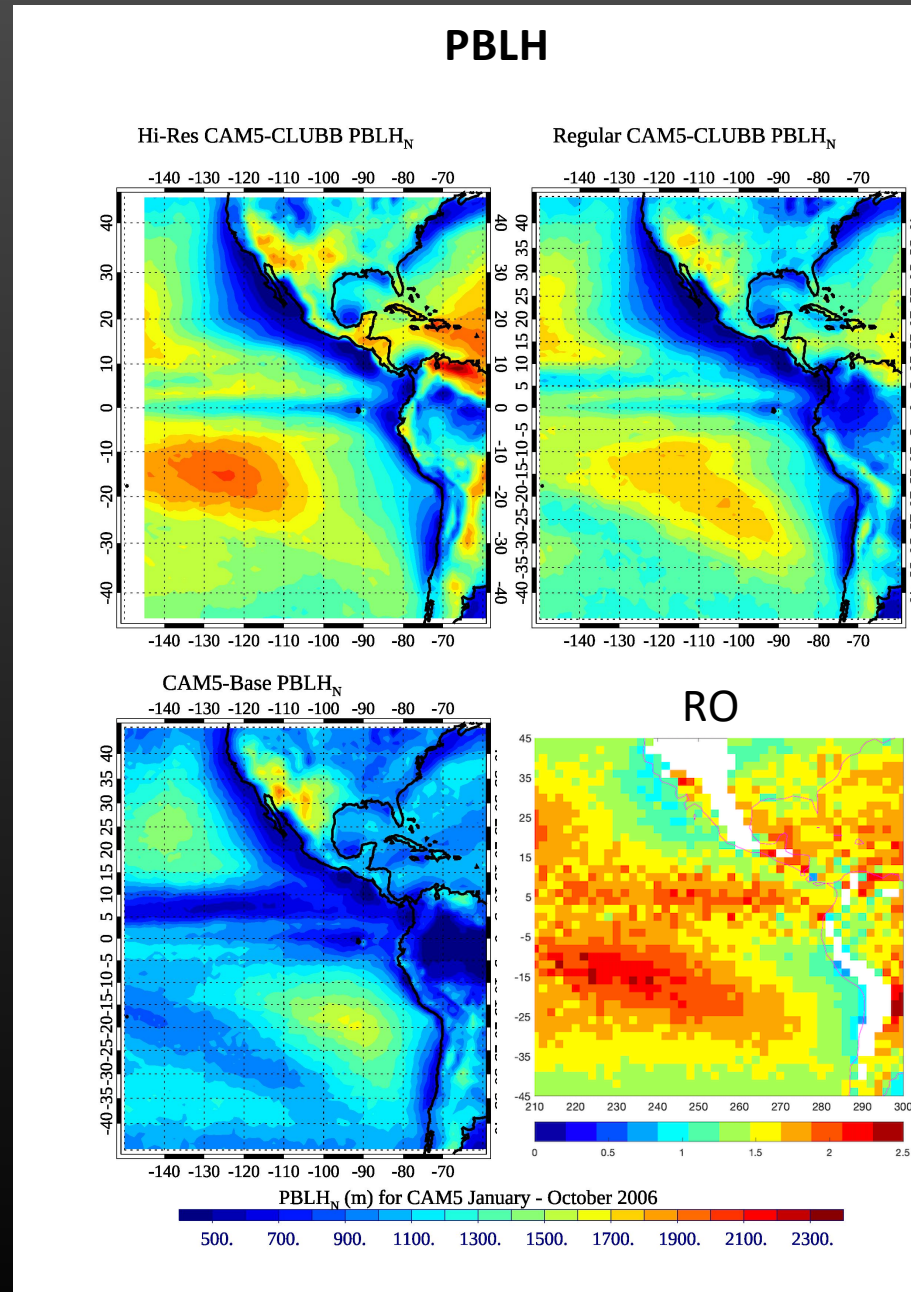
- Strong positive correlation between PBLH and DCP over the ocean.
- Distinct behavior over subtropical land (high PBLH and small DCP).

Model Results

CAM5-Base
CAM5-CLUBB
CAM5-CLUBB High Res

CAM5-CLIBB High Res yields PBLH and DCP that are most consistent with RO.

(The PBLH comparison is discussed in details in Kubar et al., GRL, 2019.)



The PBL is identified as a “Targeted Observable” in the 2017–2027 National Academy of Sciences Decadal Survey for Earth Science and Applications

“The planetary boundary layer (PBL) has broad importance to a number of Earth science priorities.... Accurate and high-resolution measurements and better understanding of boundary layer processes are of key importance for improving weather and climate models and predictions.”

TABLE S.2 Observing System Priorities

Targeted Observable	Science/Applications Summary	Candidate Measurement Approach	Designated	Explorer	Incubation
Planetary Boundary Layer	Diurnal 3D PBL thermodynamic properties and 2D PBL structure to understand the impact of PBL processes on weather and AQ through high vertical and temporal profiling of PBL temperature, moisture and heights	Microwave, hyperspectral IR sounder(s) (e.g., in geo or small sat constellation), GPS radio occultation for diurnal PBL temperature and humidity and heights; water vapor profiling DIAL lidar; and lidar** for PBL height			X

Incubation: “A new program element, focused on investment for priority observation capabilities needing advancement prior to cost-effective implementation...”

Summary

- GNSS-RO profiles provide unique information on the vertical structures of the PBL characterized by the decoupling parameter.
- Comparison with radiosondes showed very good agreement.
- The primary uncertainty comes from refractivity bias and depth penetration, which may be improved with COSMIC-2 and use of non-Abel estimation technique when ducting is present [Wang et al. 2017].
- RO has been identified as a candidate measurement for PBL, which is a Decadal Survey targeted observable in need of “incubation” in the next decade.
 - *What are the remaining uncertainties and limitations from RO?*
 - *What technological advances in RO will further improve its ability to sense the PBL?*
 - *What would a PBL mission based primarily on GNSS-RO look like?*