

Multi-Mission Multi-Center Level 1 Data Inter-Validation towards Wegener Center Reference Occultation System Reprocessing

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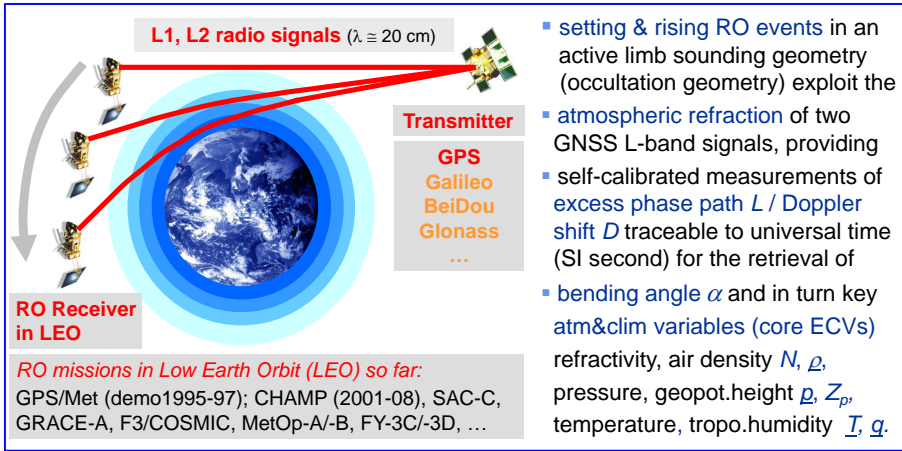
Thanks for funds to



24 Sep, 2019 – EUMETSAT ROM SAF - IROWG 2019, Helsingør, Denmark

- 1 Introduction
 - Reference Occultation Processing System
- 2 Precise Orbit Determination
- 3 Excess phase processing
- 4 Summary & Outlook

The Radio Occultation method

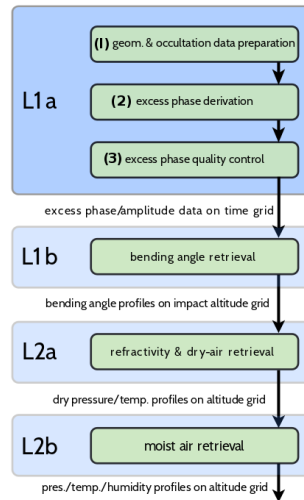
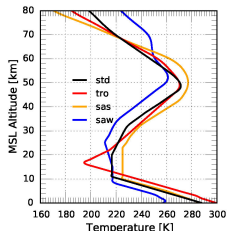
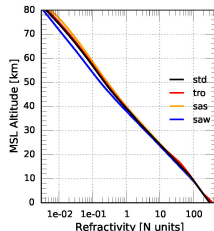
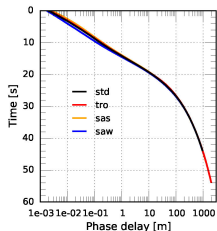


Kirchengast [2018], IGL-1



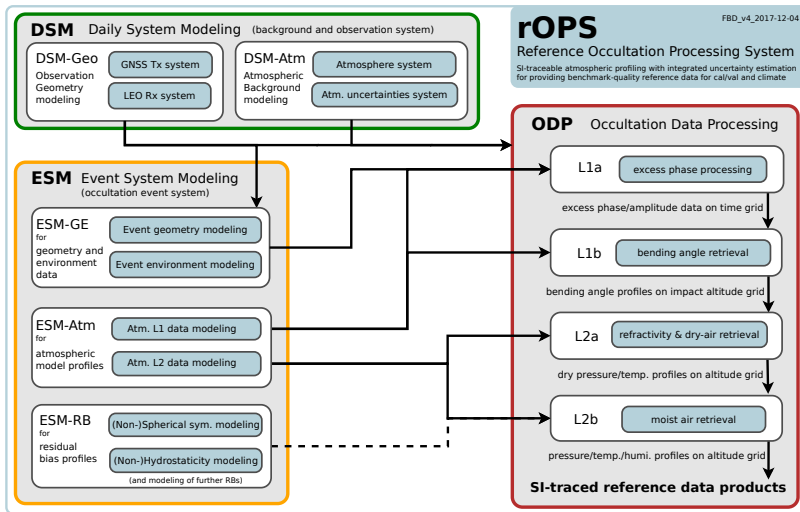
Reference Occultation Processing System

- **Reference Occultation Processing System (rOPS)**, providing reference RO data for calibration/validation and climate monitoring (Kirchengast et al. [2016], OPAC-IROWG)
- Aims to **process the full chain from the SI-tied raw data to the ECVs with integrated uncertainty propagation**: highly reversible analysis along the RO retrieval chain and its variables



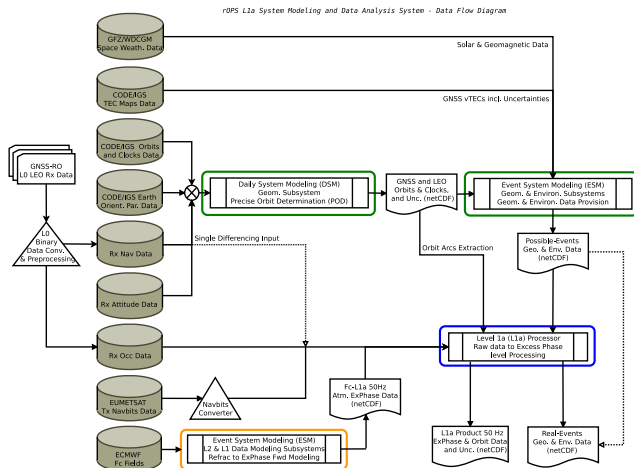


rOPS system overview

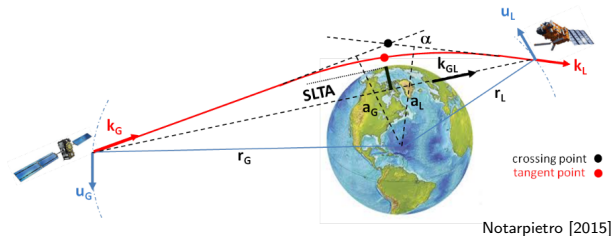




Level 1a processing scheme



Observation Geometry Modeling



- **L1a Excess Phase Processing:**
calculation of the difference between straight line propagation and real path
- **Observation Geometry Modeling:**
accurate determination of position, velocity, and clocks of GNSS and LEO satellite

GNSS and LEO orbit input data so far ...

- was provided as part of the external excess phase (L1a) products
- from CDAAC¹ and EUMETSAT²

¹<https://cdaac-www.cosmic.ucar.edu/>

²<https://eoportal.eumetsat.int/>



Precise orbit determination for GNSS-RO

- ... so why bother with an independent POD processing?
 - external orbit processing represents a blackbox
 - various differences between different solutions:
 - different software packages, force models, parameterizations ...
 - strong dependency in occultation phase data calibration:
 - measurement time-stamp correction through clock bias estimates
 - orbit position inherent to range calculation for excess phase
- ... in order to tackle this challenges we:
 - employ two independent software packages,
 - use data from different GNSS orbit archives,
 - provide measures for the orbit quality,
 - and aim at orbit uncertainties to be within 5 cm (position) and 0.05 mm/s (velocity), for highest quality of derived RO profiles

GNSS and LEO orbit input data



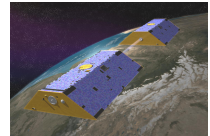
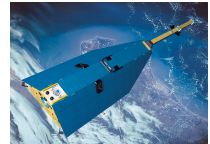
- we use data from different GNSS Orbit archives:
 - CODE³ - Center for Orbit Determination Europe
 - IGS⁴ - International GNSS Services
- LEO L0 and L1a input data from:
 - **EUMETSAT**, Darmstadt: MetOp-A/-B/-C
 - **UCAR**, Boulder: COSMIC, CHAMP, GRACE
 - **JPL**, Pasadena: CHAMP, GRACE, SAC-C
 - **GFZ**, Potsdam: CHAMP
 - **NSSC**, Beijing: FengYun-3C/-3D
 - **SPIRE**, Boulder: Lemur-2

³http://www.aiub.unibe.ch/research/code__analysis_center/index_eng.html

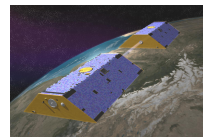
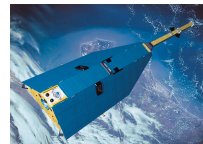
⁴<http://www.igs.org/>

Core mission details (nominal parameter)

	CHAMP	GRACE-A	Metop-A	Metop-B
Altitude	450 km	500 km	817 km	817 km
Inclination	87.2 deg	89.0 deg	98.7 deg	98.7 deg
Period	93.6 min	94.5 min	101 min	101 min
Mass	522 kg	431 kg	4093 kg	4093 kg
POD-Antenna	1	1	1	1
RO-Antenna	1	1	2	2
GPS-Receiver	BlackJack	BlackJack	GRAS	GRAS
LRA	yes	yes	no	no
Launch	2000-07-15	2002-03-17	2006-10-19	2012-09-17
Status	ended 2008	ended 2017	operational	operational



POD software

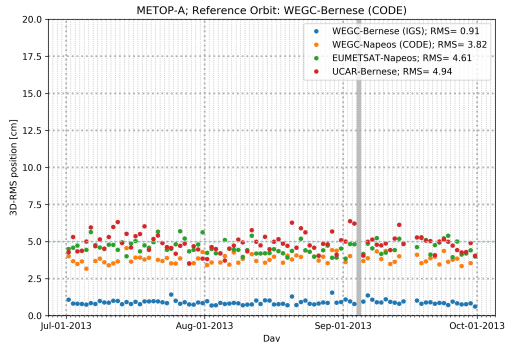


	Bernese	Napeos
Software	Bernese v5.2 (AIUB ¹)	Napeos 3.3.1 (PosiTim ²)
Arc length	24 hours	24 hours
Sampling	30 sec	30 sec

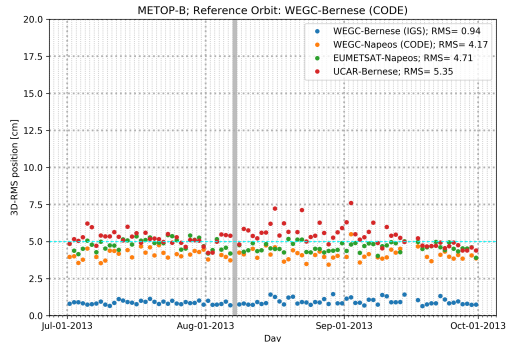
⁵<http://www.bernese.unibe.ch/>

⁶<http://www.positim.com/>

Orbit comparison - Metop-A, Metop-B

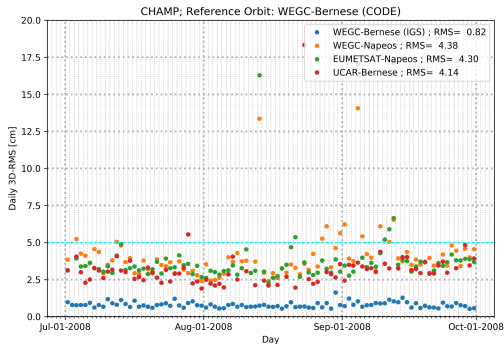


	IGS	NAP	EUM	UCAR
Radial	0.34	2.73	2.88	2.93
Along	0.68	2.16	2.61	2.93
Cross	0.49	1.57	2.49	2.69
3D	0.91	3.82	4.61	4.94

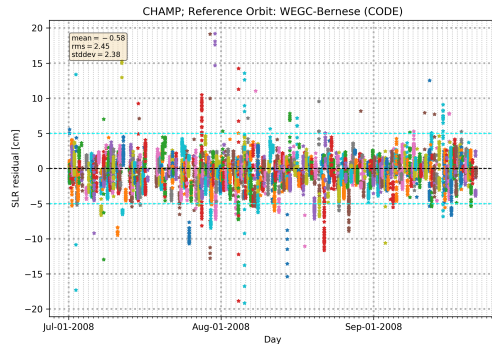


	IGS	NAP	EUM	UCAR
Radial	0.36	2.93	3.08	3.41
Along	0.71	2.57	3.00	3.46
Cross	0.51	1.49	1.95	2.24
3D	0.94	4.17	4.71	5.35

Orbit comparison - CHAMP



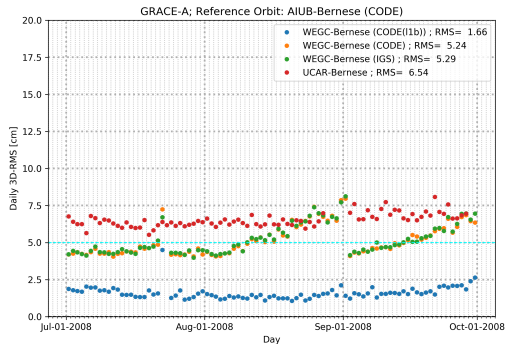
	IGS	NAP	EUM	UCAR
Radial	0.28	2.62	2.09	1.92
Along	0.58	2.51	3.23	3.43
Cross	0.46	3.34	1.58	1.40
3D	0.82	4.38	4.30	4.14



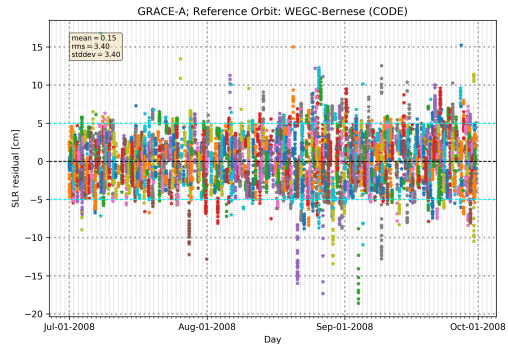
mean [cm]	stddev [cm]	RMS [cm]
-0.58	2.45	2.38

- no station selection
- elevation cut-off angle 10 degree

Orbit comparison - GRACE-A



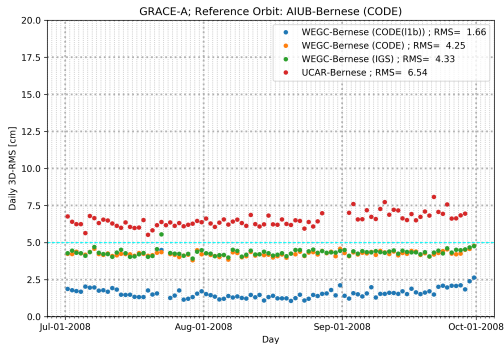
	COD(I1b)	CODE	IGS	UCAR
Radial	0.54	0.80	0.85	3.51
Along	1.47	5.27	5.16	4.56
Cross	1.15	1.22	1.44	3.12
3D	1.66	5.24	5.29	6.54



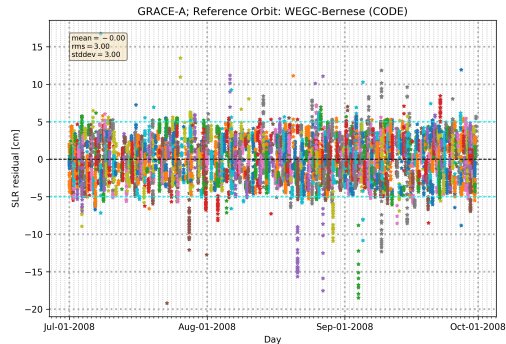
mean [cm]	stddev [cm]	RMS [cm]
0.15	3.40	3.40

- no station selection, outlier correction 20cm
- elevation cut-off angle 10 degree

Orbit comparison - GRACE-A ... improved



	COD(I1b)	CODE	IGS	UCAR
Radial	0.54	0.62	0.62	3.51
Along	1.47	4.42	4.36	4.56
Cross	1.15	1.18	1.39	3.12
3D	1.66	4.25	4.33	6.54



mean [cm]	stddev [cm]	RMS [cm]
0.00	3.00	3.00

- no station selection, outlier correction 20cm
- elevation cut-off angle 10 degree

Orbit uncertainty estimates



random uncertainty:

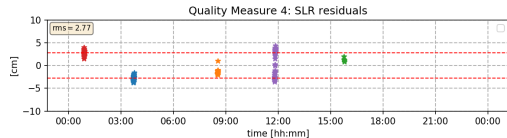
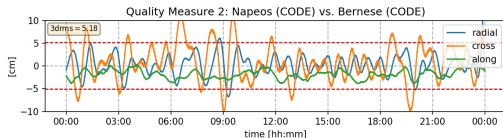
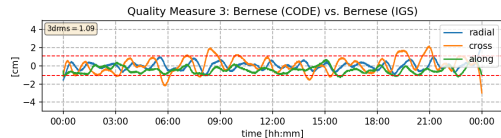
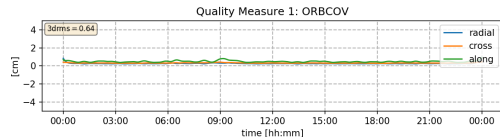
- error propagation in Bernese (ORBCOV) [Jäggi 2007]:
 - estimation essentially based on the satellite constellation only
 - optimistic estimates, hence empirical coverage factor 2 applied

systematic uncertainty:

- estimates based on the combination of:
 - the differences b/t Bernese and Napeos orbit solution
 - the differences b/t Bernese solution based on CODE and IGS input
 - SLR residuals (if satellite equipped with a laser retroreflector)

CHAMP orbit quality - "ordinary" day

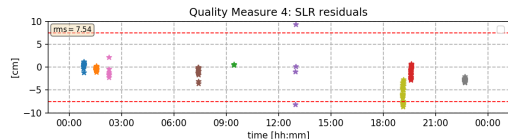
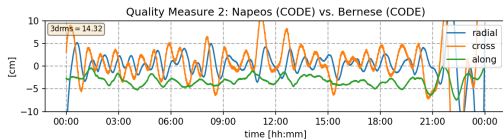
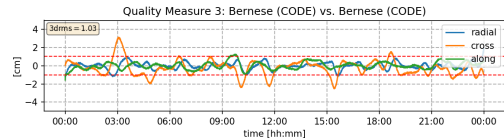
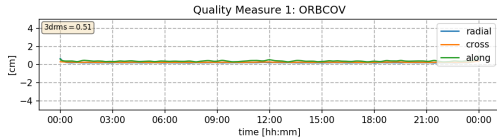
day: 2008-07-16



- all measures below 5 cm except quality measure 2 slightly exceeding the target specifications
- additional SLR measure

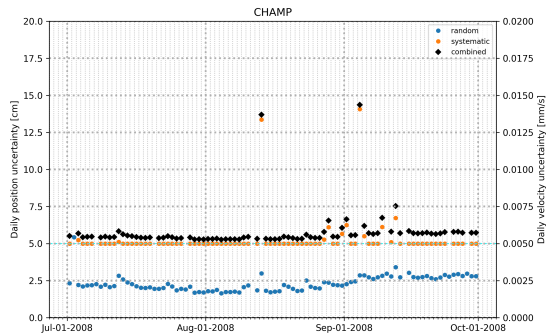
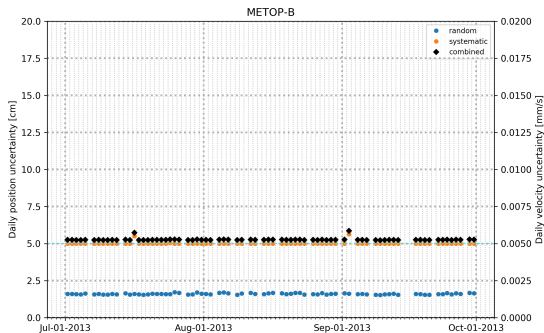
CHAMP orbit quality - "degraded" day

day: 2008-08-29



● both quality measure 2 and 4 indicate a degraded orbit solution

Daily Uncertainty Estimates - Metop-B, CHAMP



- robust uncertainty estimate time series
- single days exceeding 5 cm threshold

- periods of increased uncertainty estimates
- most of the days around 5 cm threshold

From raw phase to excess phase

$$L_r^t = \rho_r^t + c\delta_r - c\delta^t + \lambda N_r^t + \delta\rho_{r,atm}^t - \delta\rho_{r,ion}^t + \rho_{r,corr_L}^t + \epsilon_L$$

raw phase excess phase

- ρ_r^t ... geometric distance between receiver and transmitter¹
- $c\delta_r, c\delta^t$... transmitter and receiver clock biases²
- $\delta\rho_{r,atm}^t, \delta\rho_{r,ion}^t$... neutral atmosphere and ionosphere excess phase
- $\rho_{r,corr}^t$... modeled effects: relativistic effects, antenna offset & phase center corrections
- ϵ ... unmodeled errors: thermal noise, local multipath, residual cycle slips, ...
- λN_r^t ... integer phase ambiguity

¹Distance b/t receiver at receive time t and transmitter at transmission time $t - \tau$, where τ is the signal travel time.

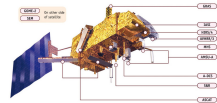
²The receiver clock bias at time t and the transmitter clock bias at time $t - \tau$.

Excess phase comparison

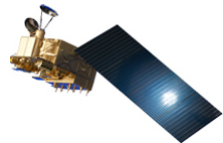
- **software:**
 - WEGC rOPS L1a processor for internal processing and conversion of external data

- **input:**
 - WEGC orbits & clocks,
 - raw occultation measurements,
 - level 1a products from:
 - WEGC, EUMETSAT, UCAR, NSSC/NSMC, Spire

- **things to consider:**
 - antenna offsets applied correctly, relativistic correction applied in POD, closed loop to open loop measurement combination, reference frames, orbit and clock interpolation ...



Courtesy: EUMETSAT

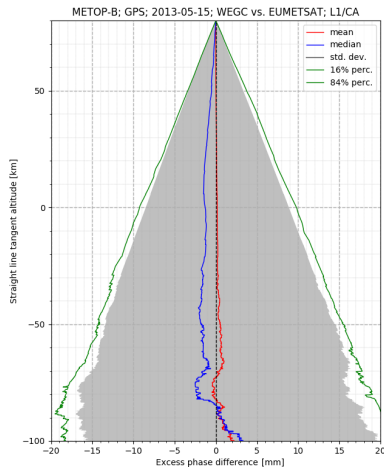


Courtesy: CMA-NSMC



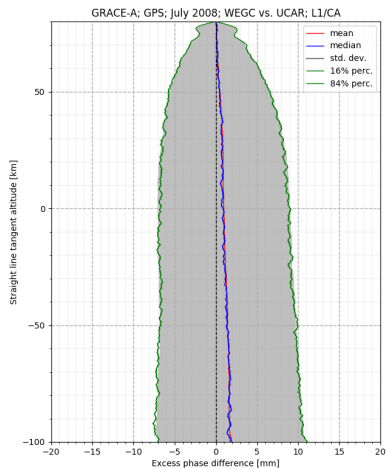
Courtesy: Spire

METOP-B; WEGC vs. EUMETSAT



- MetOp-B on May 15, 2013
- WEGC-rOPS/WEGC-Bernese vs. EUM-Yaros/EUM-Napeos
- mean difference < 1 mm
- standard deviation < 15 mm

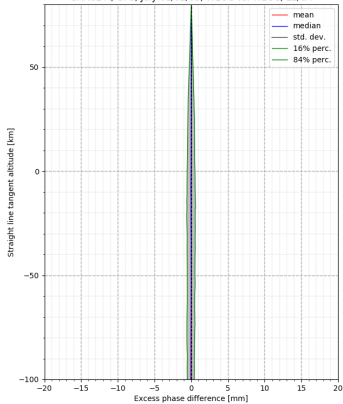
GRACE-A; WEGC vs. UCAR



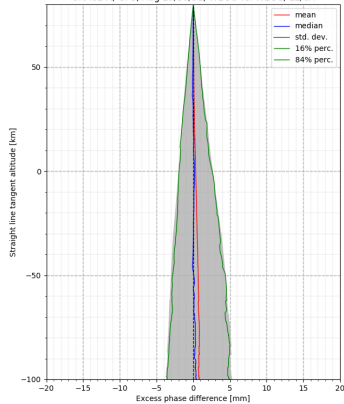
- GRACE-A July 2008
- WEGC-rOPS/WEGC-Bernese vs. UCAR-atmPhs/UCAR-Bernese
- mean difference < 2 mm
- standard deviation < 10 mm

GRACE-A; orbit degradation

GRACE-A; GPS; July 01/02/03; WEGC vs. WEGC; L1/CA



GRACE-A; GPS; Aug 29/30/31; WEGC vs. WEGC; L1/CA



- GRACE-A Jul 01-03, 2008 (left); 'ordinary' POD
- GRACE-A Aug 29-31, 2008 (right); 'degraded' POD
- comparison using WEGC-rOPS, but different orbit and clock input
- increased mean and stddev for 'degraded' case

Summary and Outlook



- the **rOPS** with focus on the **DSM-Geo modeling** and **ODP-L1a processing**, comprising the **LEO POD** and **excess phase processing**, was introduced
- **orbit** and **excess phase intercomparison** acknowledge the **quality of WEGC POD LEO orbit** output
- the POD subsystem delivers **reliable orbit and clock products** including **uncertainty estimates**
- the **rOPS excess phases** show a high consistency compared to existing processing systems from EUMETSAT and UCAR.

next steps, ongoing ...

- analyze and characterize uncertainty of the **excess phase processing**
- processing of test month ensembles of **FY-3C (JLOAC)** and **Spire** (ESA study) data
- support the **reprocessing** of MetOp, CHAMP, GRACE, COSMIC data by **rOPS**

Thank you for your attention!

References



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