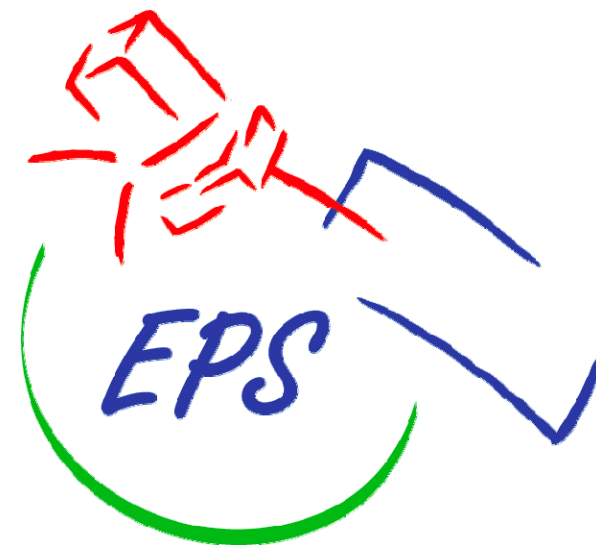


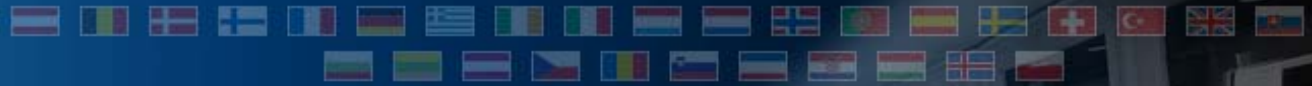


# GRAS Status and possible future European RO Mission / Cooperation

**GRAS Team at EUMETSAT**  
(Contact: [Axel.vonEngeln@eumetsat.int](mailto:Axel.vonEngeln@eumetsat.int))



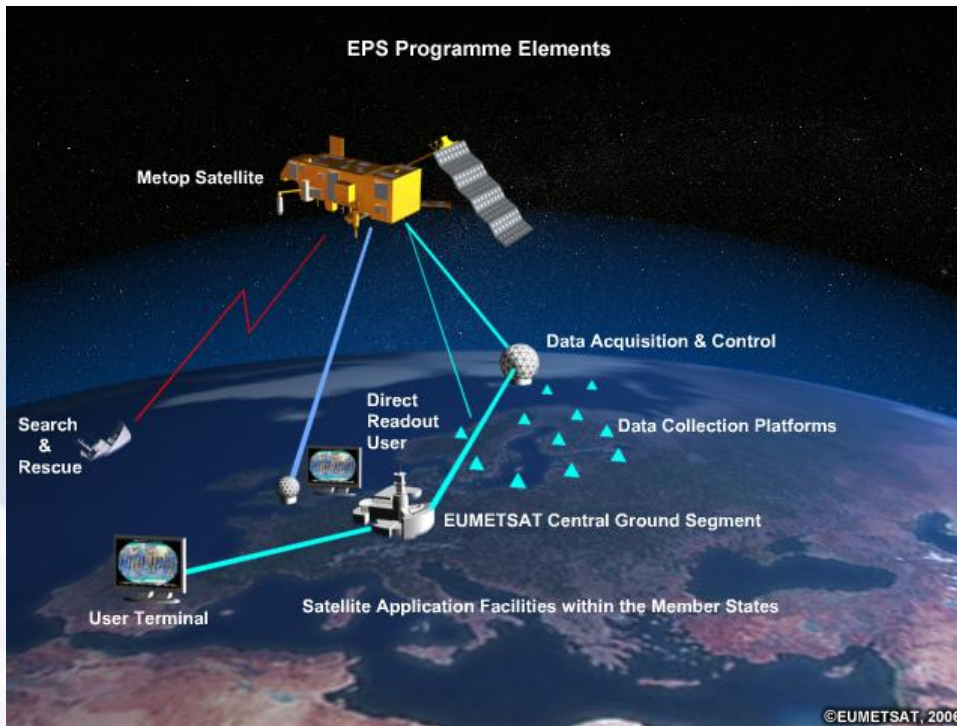
# Overview



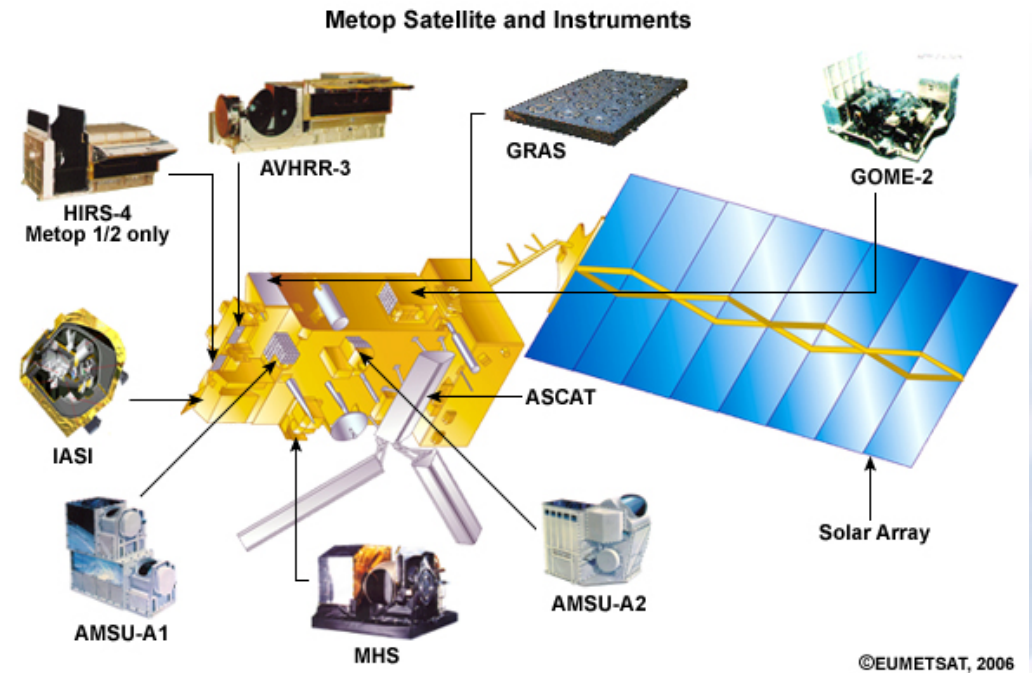
- **EUMETSAT Polar System**
- **GRAS Instrument**
- **Future Radio Occultation Missions / Cooperation**
- **Summary**

# EUMETSAT Polar System

## Programme Elements



## Space Segment



# GRAS Instrument

## GRAS Fact Sheet

### GPS channels:

- 2 rising, 2 setting (atm.)
- 8 zenith channels (orbit)

### observations:

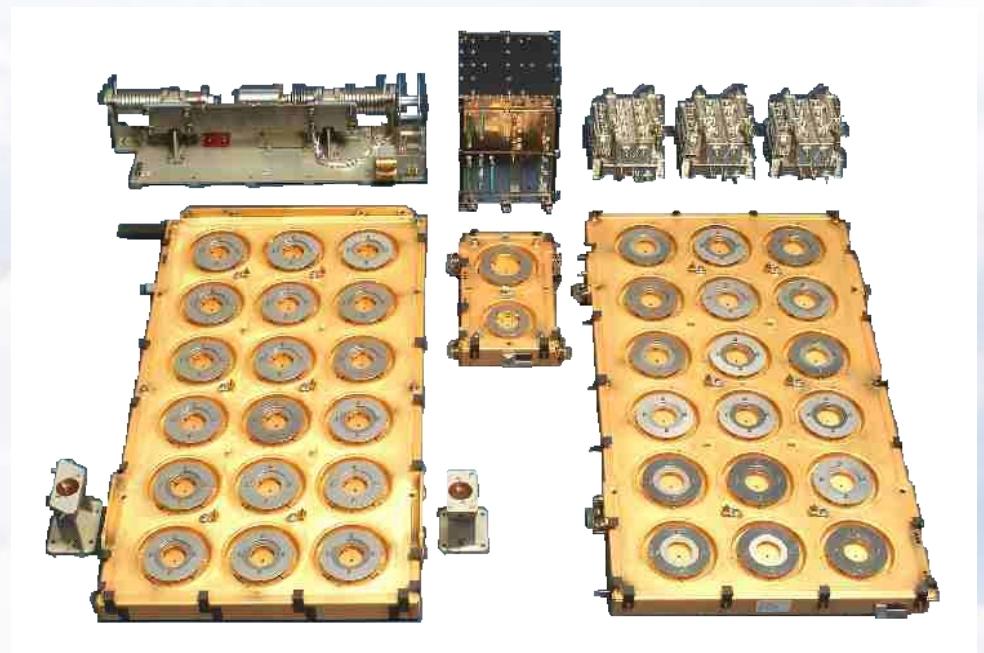
- > 600 profiles / day

### level 1b products:

- bending angle

### level 2 products:

- temperature
- water vapour
- climate applications



GRAS Instrument Components

# GRAS Processing

## Input:

- Measurement data from Svalbard ground station
- GPS Clocks and Orbit Data from support network

## 1. Metop orbit processing:

- 1min sequential processing of clocks and orbits

## 2. Bending angle processing:

- Zero differencing
- Geometrical optics
- Dual frequency tracking
- Open loop data not yet included

# GRAS Products and Timeliness

## **L1B provided by EUMETSAT in Near Real Time (2h 15 min):**

- thinned bending angles on GTS: BUFR
- bending angles on EUMETCast: BUFR, EPS

## **L2 provided by GRAS SAF in Near Real Time (3h):**

- thinned refractivities, temperature on GTS: BUFR

## **Climate data provided by EUMETSAT / GRAS SAF offline:**

- re-processing of orbits, phases at EUMETSAT and re-processing at GRAS SAF for climate applications (currently planned)

# Brief History on the GRAS Instrument

- **Metop launch on 19 October 2006**
- **GRAS instrument switch on 26 October 2006**
- **entering navigation mode on 26 October 2006**
- **first setting occultation 27 October 2006 (07:12 UTC)**
- **first rising occultation 27 October 2006 (07:17 UTC)**

**Since then the instrument worked very reliable with just a few outages.**

# Brief History on the GRAS Data Processing

- data dissemination in test mode from May 2007 (restricted)
- data declared pre-operational 19 February 2008
- data declared operational 15 April 2008 (PPF Version 2.10)

Since then several improvements of the processor, currently we run version 2.11 with 2.12 in the making.

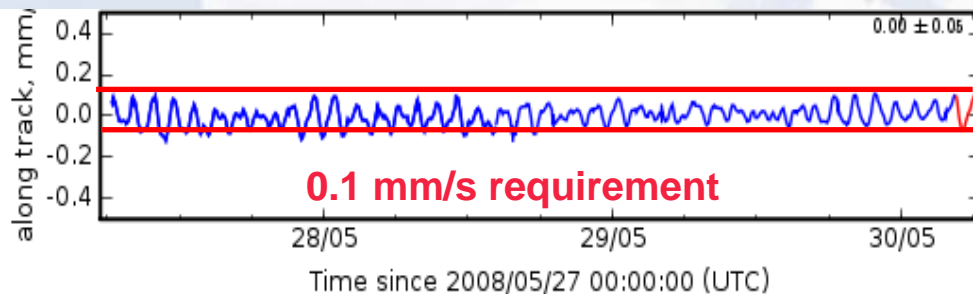


# GRAS Processor Update & Monitoring

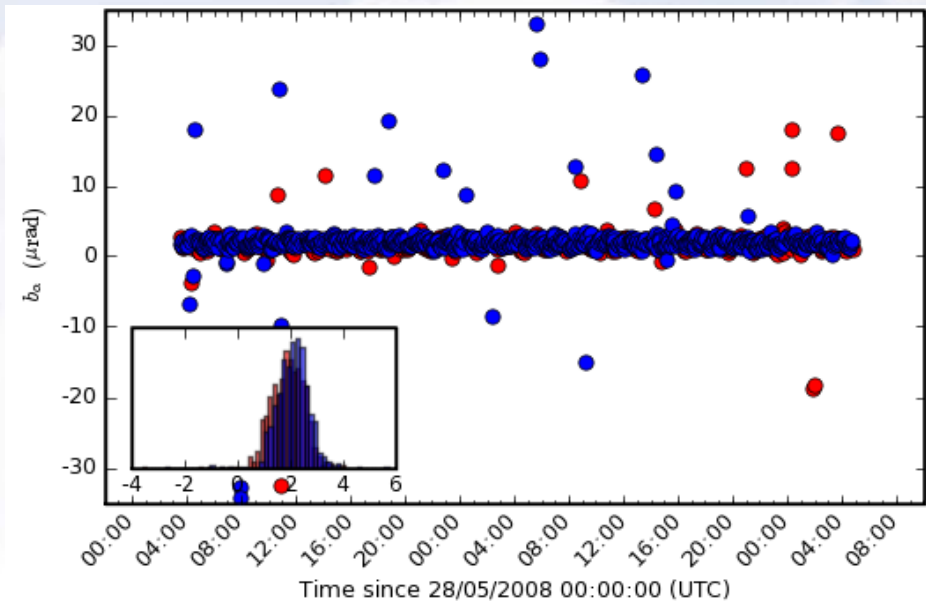
## Installation Process:

1. Offline Testing
2. Installation on Testing Platforms
3. Installation on Operational Platform

## Orbit: Along Track Velocity

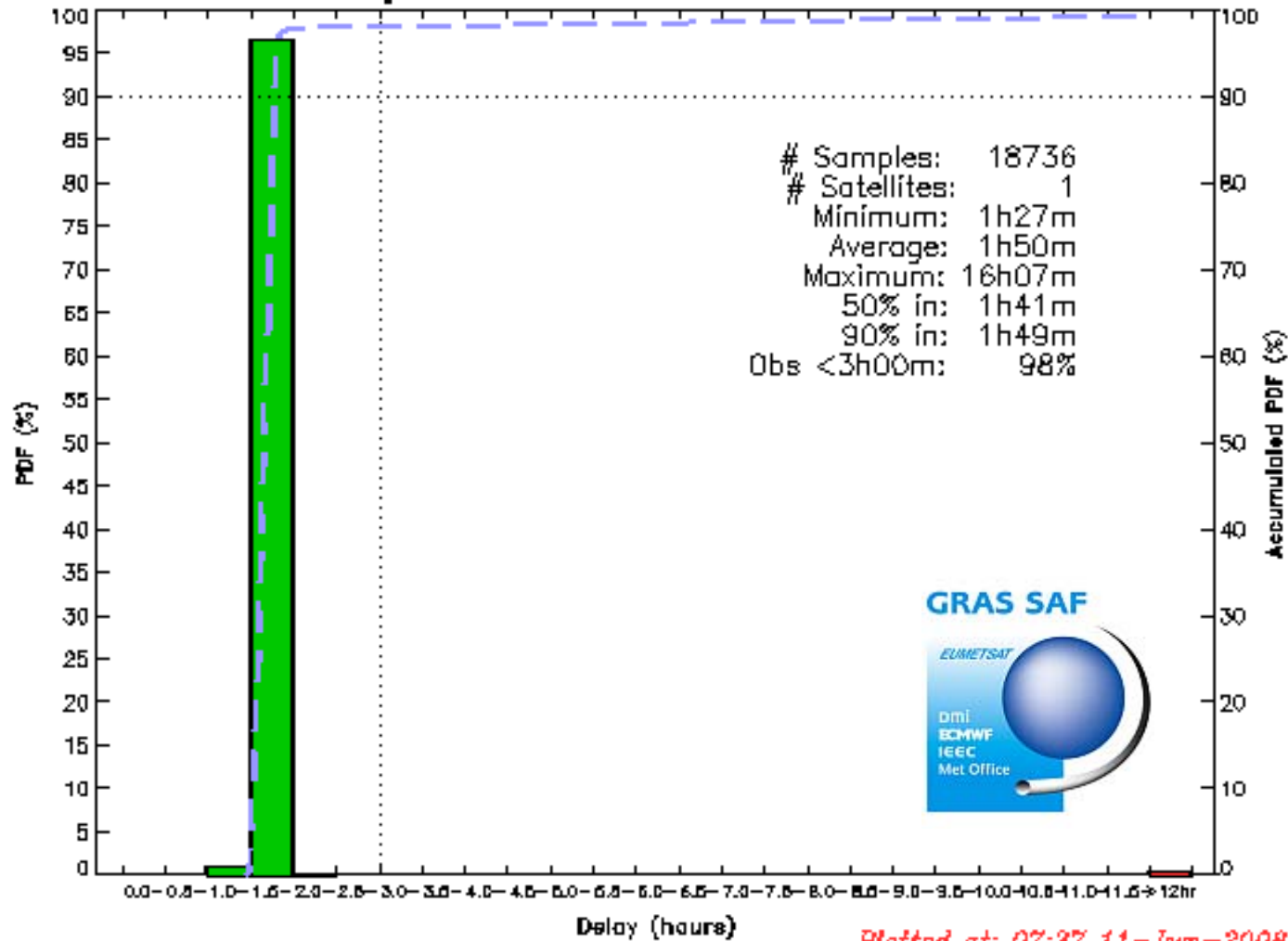


## Bending Angle: Bias



# GRAS SAF Monitoring of Timeliness

META-DMI Delays for 00:00 14-MAY-2008 to 23:56 10-JUN-2008



Plotted at: 07:37 11-Jun-2008

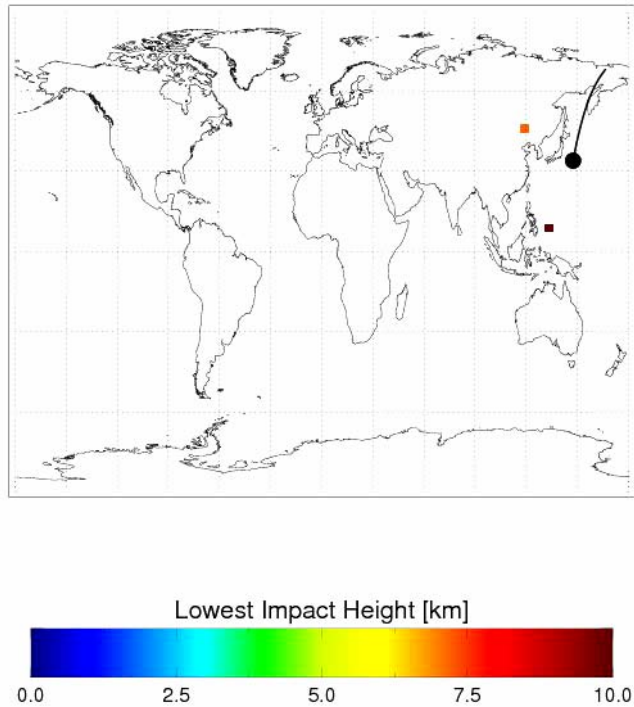
GRAS SAF Workshop on RO Applications, EMWF, June 2008



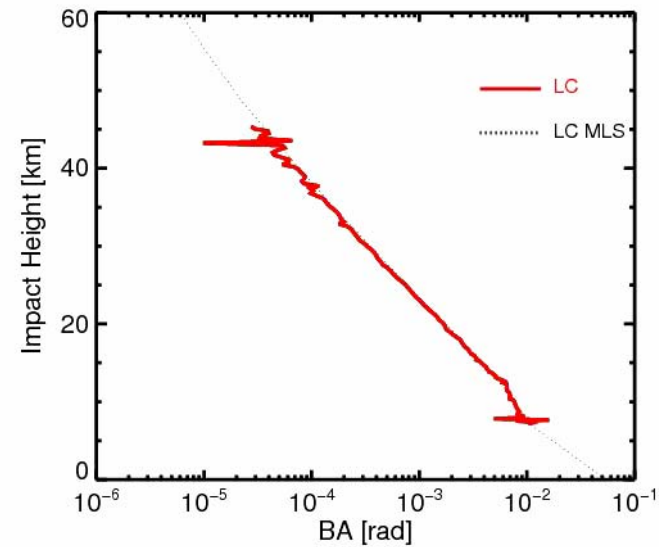
GRAS timeliness measured at UK Met Office, taken from: [monitoring.grassaf.org](http://monitoring.grassaf.org)



# GRAS Measurement Animation

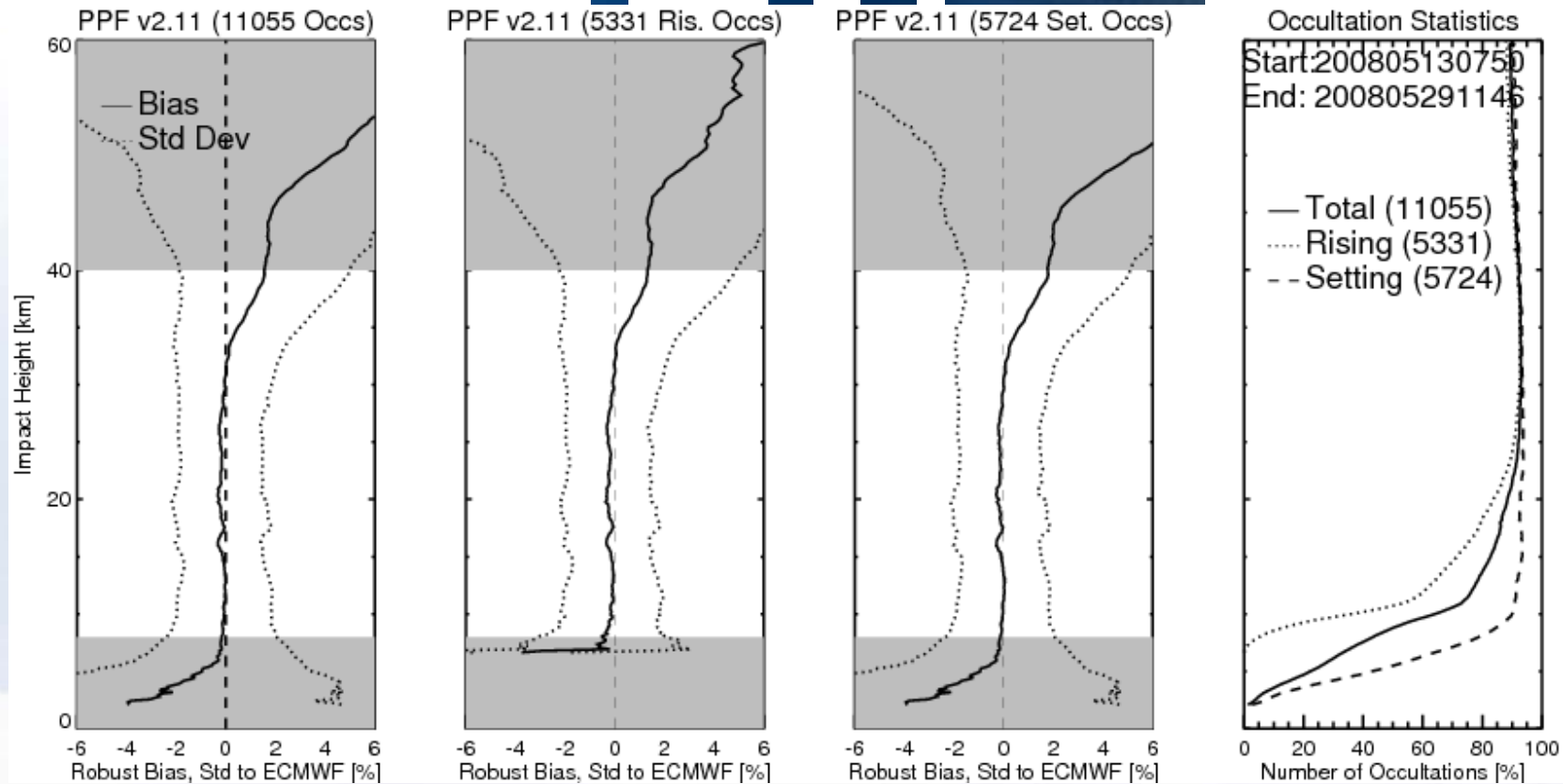


Date: 2008/05/26 00:02  
Total: 002  
Type: Setting  
Lat / Lon: 45.8 / 119.1



PPF 2.11 Data

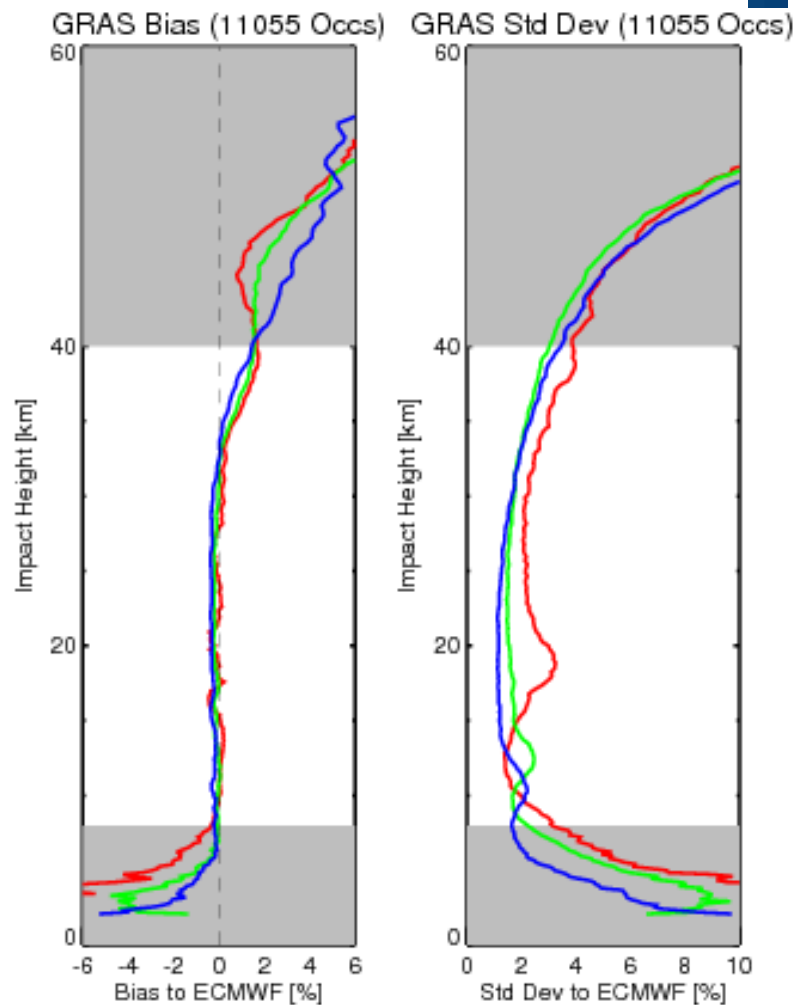
# PPF 2.11 Validation against ECMWF



**Left: all occultations; Middle left: rising ones; Middle right: setting ones (Solid line bias, dotted line standard deviation); Right: Percentage of occultations entering statistics (robust stats, de-weighting outliers). Grey areas: used for POD monitoring (top); affected by multi-path and geometrical optics retrieval (bottom).**



# PPF 2.11 Validation against ECMWF (by Latitude)



Start: 200805130750  
End: 200805291146

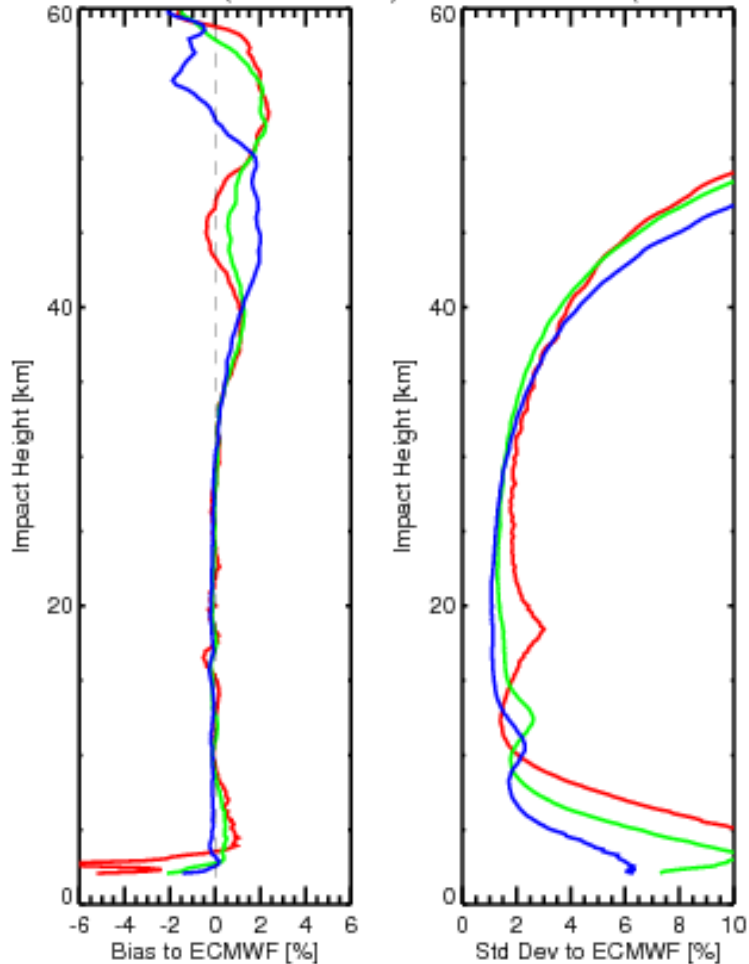
— Low Lat (3840)  
— Mid Lat (4290)  
— High Lat (2925)

*Left: bias against ECMWF; Right: standard deviation against ECMWF (robust stats, de-weighting outliers). Grey areas: used for POD monitoring (top); affected by multi-path and geometrical optics retrieval (bottom).*



# COSMIC Validation against ECMWF (by Latitude)

COSMIC Bias (50515 Occs) COSMIC Std Dev (50515 Occs)



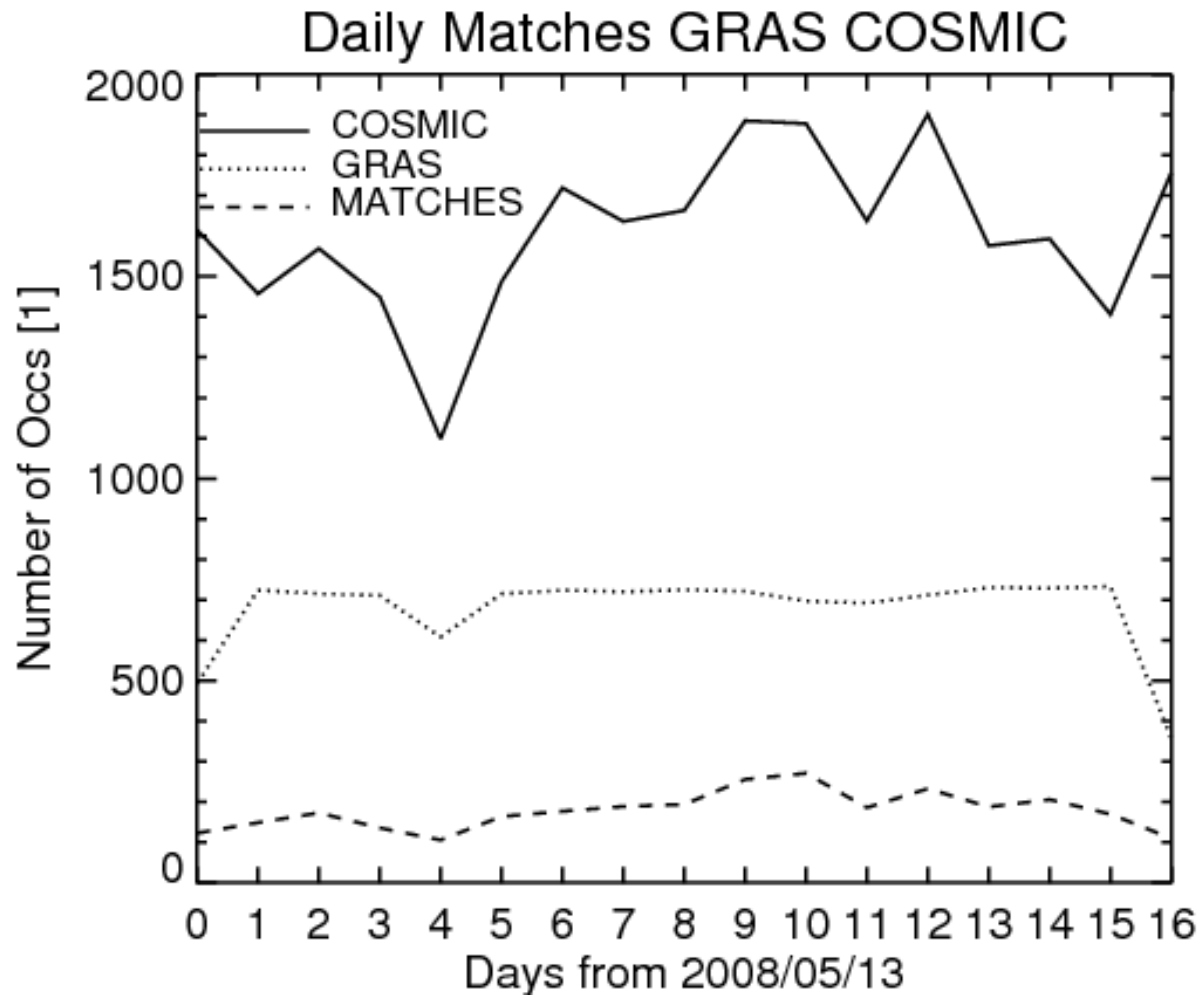
Start: 200804302358

End: 200805312359

- Low Lat (15902)
- Mid Lat (24193)
- High Lat (10420)

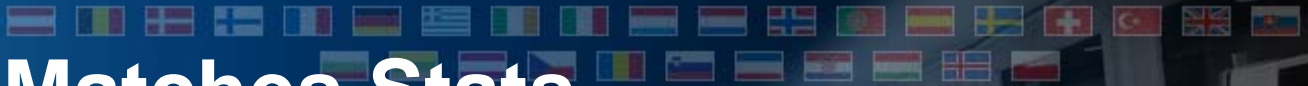
*Left: bias against ECMWF; Right: standard deviation against ECMWF (robust stats, de-weighting outliers).*

# GRAS COSMIC Matches Daily

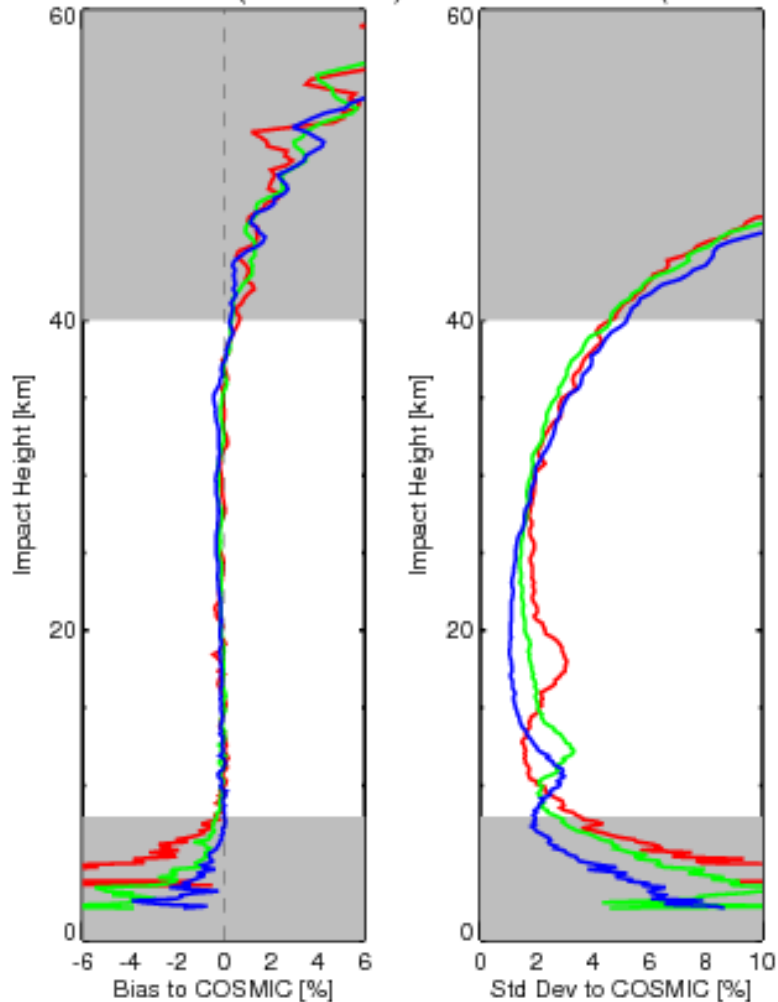


- ~17 days in May 08
- v2.11 (GS3, no QC)
- COSMIC raw
- 300 km / 3 hours

# GRAS COSMIC Matches Stats



Matches Bias (2951 Occs) Matches Std Dev (2951 Occs)



Start: 200805130757  
End: 200805291117

— Low Lat (649)  
— Mid Lat (1236)  
— High Lat (1066)

*Left: bias against COSMIC; Right: standard deviation against COSMIC (robust stats, de-weighting outliers). Grey areas: used for GRAS POD monitoring (top); affected by GRAS multi-path and geometrical optics retrieval (bottom).*



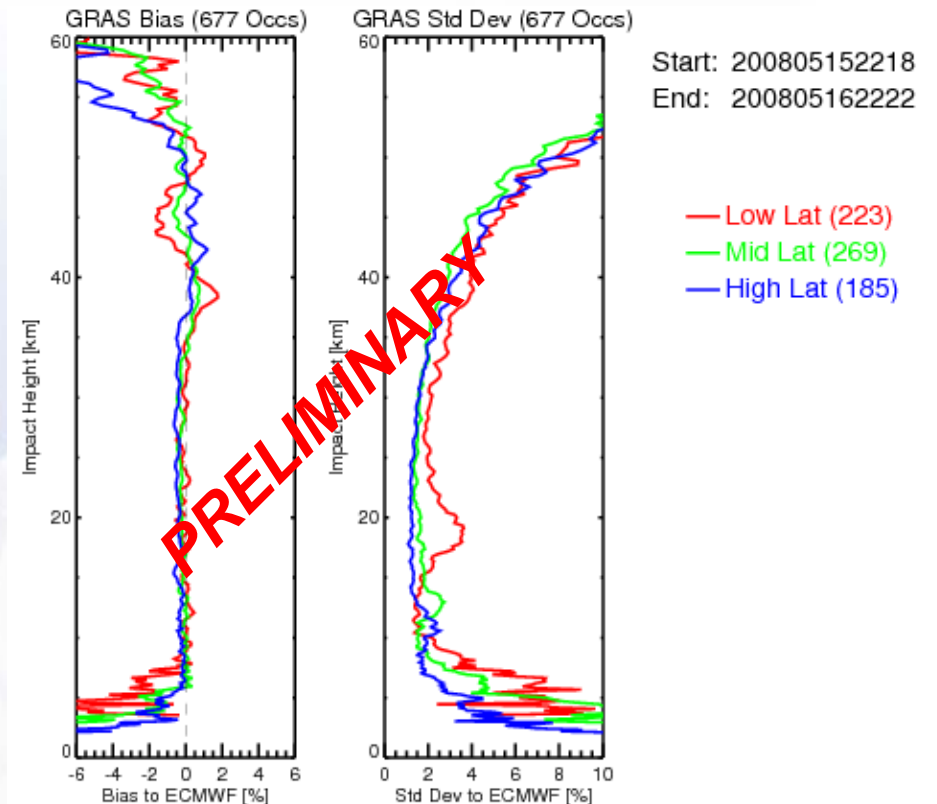
# PPF 2.12 Outlook

## Plans to include:

- improved QC for bending angles
- QC flagging of orbit resets

## Likely not possible:

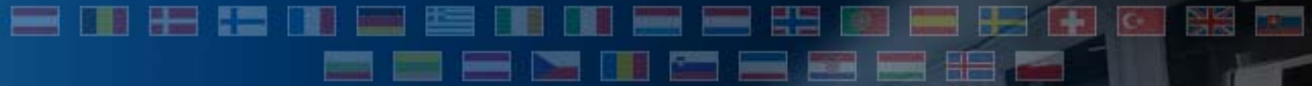
- correct antenna position / orbit



# Possible future European RO Mission / Cooperation

- **Metop:**
  - GRAS will be flying up to 2020 on Metop A-C !!
- **Post-EPS:**
  - radio occultation mission is discussed
- **COSMIC Cooperation:**
  - currently provide station data (GSN)

# Summary



- **GRAS Instrument:**
  - excellent performance up to ~ 40 km
  - excellent timeliness
  - data is assimilated into ECMWF model
  - lower troposphere needs raw sampling / wave optics
  - improvements to quality flags scheduled
- **Future of RO in Europe:**
  - a lot more GRAS data coming the next years
  - RO is one possible mission in Post-EPS program